

New perspective on Sine-Gordon model and perturbative QFT

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¹Joint work with Dorothea Bahns.

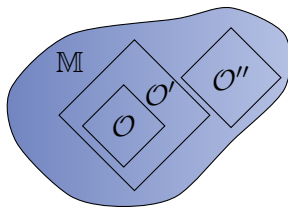
Outline of the talk

- 1 Algebraic QFT and its generalizations
 - Outline of the pAQFT framework
 - Scalar field

- 2 The Sine-Gordon model

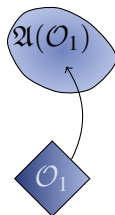
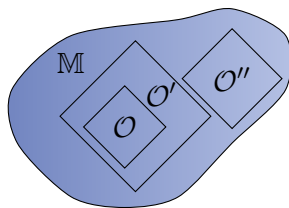
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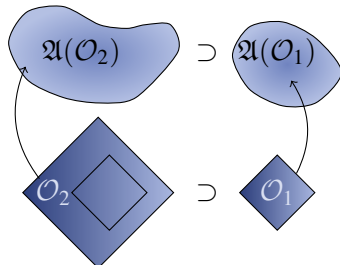
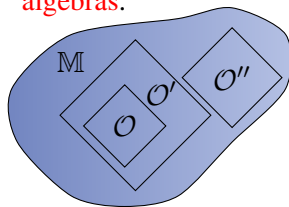
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- **Haag-Kastler** idea: a model is defined by associating to each bounded contractible region \mathcal{O} of Minkowski spacetime \mathbb{M} the algebra $\mathfrak{A}(\mathcal{O})$ of observables that can be measured in \mathcal{O} .



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- The physical notion of subsystems is realized by the condition of **isotony**, i.e.: $\mathcal{O}_1 \subset \mathcal{O}_2 \Rightarrow \mathfrak{A}(\mathcal{O}_1) \subset \mathfrak{A}(\mathcal{O}_2)$. We obtain a **net of algebras**.



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where $[\cdot, \cdot]$ is the commutator in the sense of $\mathfrak{A}(\mathcal{O}_3)$, where \mathcal{O}_3 contains both \mathcal{O}_1 and \mathcal{O}_2 .

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- This is a QFT version of the initial value problem (or local constancy in the time direction).

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- For a review see the book: *Perturbative algebraic quantum field theory. An introduction for mathematicians*, KR, Springer 2016.

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- Construction of the local net of observables in Sine-Gordon model: D. Bahns, KR, [[arXiv:math-ph/1609.08530](https://arxiv.org/abs/1609.08530)].

Scalar field: free dynamics

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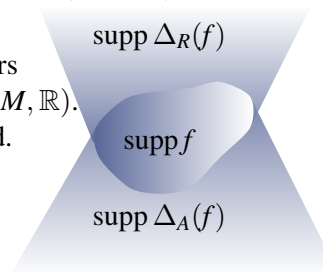
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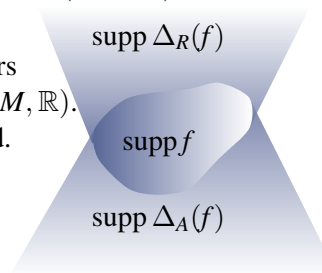
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- P has retarded and advanced Green operators $\Delta_R, \Delta_A : \mathcal{D}(M) \rightarrow \mathcal{E}(M)$, where $\mathcal{D} \equiv \mathcal{C}^\infty(M, \mathbb{R})$. They satisfy: $P \circ \Delta_{R/A} = \text{id}$, $\Delta_{R/A} \circ P = \text{id}$.



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- Their difference is the causal propagator $\Delta \doteq \Delta_R - \Delta_A$.



Poisson structure and the \star -product

- The Poisson (Peierls) bracket of the free theory is

$$\{F, G\} \doteq \left\langle \frac{\delta F}{\delta \varphi}, \Delta \frac{\delta G}{\delta \varphi} \right\rangle .$$

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- The free QFT is defined as $\mathfrak{A}_0(\mathcal{O}) \doteq (\mathcal{F}(\mathcal{O})[[\hbar]], \star, *)$, where $F^*(\varphi) \doteq \overline{F(\varphi)}$ and $\mathcal{F}(M)$ is an appropriate functional space.

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- Define the time-ordered product $\cdot_{\mathcal{T}}$ on $\mathcal{F}_{\text{reg}}(M)[[\hbar]]$ by:

$$F \cdot_{\mathcal{T}} G \doteq \mathcal{T}(\mathcal{T}^{-1}F \cdot \mathcal{T}^{-1}G)$$

Interaction

- We have $(\mathcal{F}_{\text{reg}}(M)[[\hbar]], \star, \cdot_{\mathcal{T}})$, where \star is non-commutative, $\cdot_{\mathcal{T}}$ is commutative and they satisfy the relation

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- Renormalization problem: **extend $\cdot_{\mathcal{T}}$ to local non-linear functionals.**

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- The 2-point function of the free massless scalar field in 2D coincides with the Hadamard parametrix

$$W(x) = \frac{i}{2}(\Delta_R(x) - \Delta_A(x)) + H(x) = -\frac{1}{4\pi} \ln \left(\frac{-x \cdot x + i\epsilon t}{\mu^2} \right)$$

where $\mu > 0$ is the scale parameter that we need to fix.

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- In particular, for $\mathbf{x} = \mathbf{y}$ and $t > t'$,

$$V_a(t, \mathbf{x}) \star V_{a'}(t', \mathbf{x}) = e^{aa' i \hbar / 2} V_{a'}(t', \mathbf{x}) \star V_a(t, \mathbf{x}) ,$$

which is the well-known relation for vertex operators.

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$$\text{where } \alpha_{H_v} \doteq e^{\frac{\hbar}{2} \left\langle H_v, \frac{\delta^2}{\delta \varphi^2} \right\rangle}.$$

- Hence \star , and \star_v are equivalent products, and α_{H_v} , is a “gauge transformation”.

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- Similar for the S -matrix:

$$\omega_v(\mathcal{S}(\lambda :V:_v)) \doteq \alpha_v \left(e^{\frac{i\lambda}{\mathcal{T}} :V:_v / \hbar} \right) (0) = e^{\frac{i\lambda V}{\mathcal{T} \hbar}}(0).$$

Here $\cdot_{\mathcal{T}_v}$ is the time-ordered product corresponding to \star_v .

Convergence of the S -matrix

Theorem (Bahns, KR 2016)

The formal S -matrix $\alpha_v \circ \mathcal{S}(\lambda : V :_v) = e_{\mathcal{T}_v}^{i\lambda V/\hbar}$ in the Sine-Gordon model with $V = \frac{1}{2}(V_a(f) + V_{-a}(f))$ and $0 < \beta = \hbar a^2/4\pi < 1$, $f \in \mathcal{D}(M)$, converges as a functional on the configuration space.

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- The abstract formal S -matrix is constructed before a state is chosen.
- Local observables are constructed using the Bogoliubov formula and one obtains an interacting local net $\mathfrak{A}(\mathcal{O})$.

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- Apply the same methods to a larger class of integrable models and other models in 2D.
- Show equivalence with the $\mathcal{O}(3)$ model and the Thirring model.



Thank you very much for your attention!